

## Physics Formulas for Chapters 2 - 8

### Simple Kinematic Formulas

$\Delta x = v_{average} \times t$  Where  $\Delta x$  is distance and  $t$  is time and  $v$  is velocity or speed.

### General Kinematic Formulas: The Big Three Formulas for uniformly accelerated motion

$$v_f = v_i + at \quad \Delta x = v_i t + \frac{1}{2} at^2 \quad v_f^2 = v_i^2 + 2a\Delta x \quad g = 9.8 \frac{m}{s^2} \quad \text{or you can use } g=10 \text{ m/s}^2$$

$a$ =acceleration and  $g$  is acceleration due to gravity.  $\Delta x$  can be substituted as  $\Delta y$  for vertical distances.

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$$F_{net} = ma \quad \text{Weight} = mg \quad F_f = \mu N$$

Objects in equilibrium:  $\sum F_x = \text{Zero}$  and  $\sum F_y = \text{Zero}$

Objects accelerating:  $\sum F = ma$

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Work =  $F \times d$  Where  $d$  = distance or  $\Delta x$        $Work = Fd * \cos\theta$

$$W = Fd = \frac{1}{2}mv_f^2 - \frac{1}{2}mv_i^2 \quad \text{or} \quad Fd = mgh_f - mgh_i \quad PE_g = mgh \quad KE = \frac{1}{2}mv^2$$

Conservation of Mechanical Energy (ME) – no non-conservative forces like friction present

$$ME_i = ME_f \quad PE_i + KE_i = PE_f + KE_f \quad mgh_i + \frac{1}{2}mv_i^2 = mgh_f + \frac{1}{2}mv_f^2$$

Power:  $P = \frac{Work}{t}$        $P = F \times v$       1 Watt = 1 J/s

For Pre-AP: Chapter 10 and 11

$Q = mC\Delta T$        $C$  = specific heat      System energy and work:  $U_f = U_i + Q_{in} + W_{in} - W_{out} - waste$

$eff = \frac{Work_{out}}{Work_{in}}$       If want percent, then multiply  $eff.$  times 100

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### **Ch. 6: Momentum is $p$**

$p = mv$       impulse =  $\Delta p$  or  $\Delta mv$  and impulse =  $F \times t$       so       $F \times t = \Delta mv$

Conservation of Momentum – as long as no external force acts on system, total momentum is conserved.       $P_i = P_f$

For two separate objects (#'s 1 and 2):       $m_1v_{1i} + m_2v_{2i} = m_1v_{1f} + m_2v_{2f}$

For two objects (#'s 1 and 2) that finally stick together:       $m_1v_{1i} + m_2v_{2i} = (m_1 + m_2)v_f$

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### Ch. 7-8: Circular motion and torque

$$v = \frac{2\pi r}{T} \quad v = 2\pi r f \quad T = \text{period} \quad f = \text{frequency} \quad T = \frac{1}{f} \quad \text{and} \quad f = \frac{1}{T} \quad a_c = \frac{v^2}{r} \quad F_c = ma_c$$

$$F_G = G \frac{m_1 M_2}{r^2} \quad v = \sqrt{\frac{GM}{r}} \quad G = \text{Gravitational constant}$$

$$\tau \text{ (Tau) is torque} \quad \tau = rF \quad r \text{ is lever arm distance} \quad G = 6.67 \times 10^{-11} \frac{N \cdot m^2}{kg^2}$$

$\omega$  (omega) is rotational or angular speed (# of revolutions or rotations per unit of time)

I is moment of inertia (inertia of rotating mass) Angular momentum =  $I\omega$

Conservation of Angular Momentum  $I_1\omega_1 = I_2\omega_2$

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