

Physics Formulas for Units 2-6

Unit 2 Simple Kinematic Formulas

Constant motion: only used with average velocity or with constant velocity!!

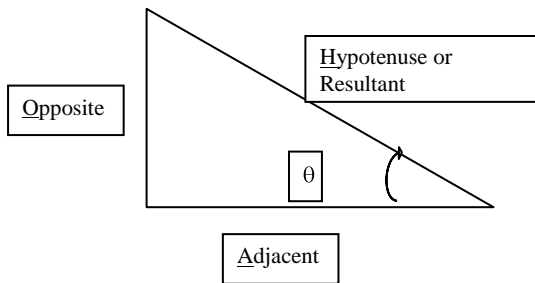
A constant velocity IS an average velocity and IS the instantaneous velocity every second that the object is in constant motion

$$\Delta x = v_{average} \times t$$

Units 3-4: Acceleration and projectile motion

General Kinematic Formulas: **The Big Three Formulas** for uniformly accelerated motion

$$v_f = v_i + at \quad v_f^2 = v_i^2 + 2a\Delta x \quad \Delta x = v_i t + \frac{1}{2}at^2 \quad g = 9.8 \frac{m}{s^2} \text{ or you can use } g=10 \text{ m/s}^2$$



$$\sin \theta = O/H \quad \cos \theta = A/H \quad \tan \theta = O/A$$

To get the side opposite in a right triangle: side opposite = Hypotenuse (Sin θ)

To get the side adjacent: side adjacent = Hypotenuse (Cos θ)

If $W = mg$ is the hypotenuse, then the adjacent would be = $mg (\cos \theta)$ and opposite side would be = $mg (\sin \theta)$

Unit 5: Newton's laws and forces

$$F_{net} = ma \quad W = mg \quad F_g = G \frac{m_1 m_2}{r^2} \text{ when } G = 6.67 \times 10^{-11} \frac{N \cdot m^2}{kg^2}$$

$$F_f = \mu_k F_N \quad \text{For kinetic friction} \quad \mu \text{ is the coefficient of friction and can be } \mu_k \text{ OR } \mu_s$$

N or F_N are symbols for the Normal Force in a formula

$$F_f \leq \mu_s N \quad \text{For static friction}$$

Force of static friction will be at maximum and equal to $\mu_s N$ right before the object begins to slide.

Objects in equilibrium: $\sum F_x = \text{Zero}$ and $\sum F_y = \text{Zero}$

Objects accelerating: $\sum F = ma$

Unit 6: Circular motion

Tangential velocity formulas

$$v = \frac{2\pi r}{T} \quad T = \text{period} \quad v = 2\pi r f \quad f = \text{frequency} \quad T = \frac{1}{f} \quad \text{and} \quad f = \frac{1}{T}$$

$$a_c = \frac{v^2}{r} \quad a_c = \text{centripetal acceleration} \quad F_c = ma_c$$

$$F_G = G \frac{m_1 M_2}{r^2} \quad v = \sqrt{\frac{GM}{r}} \quad G = \text{Gravitational constant} = G = 6.67 \times 10^{-11} \frac{N \cdot m^2}{kg^2}$$

τ (Tau) is torque $\tau = rF$ r is lever arm distance

ω (Omega) is rotational speed or angular velocity $\omega = \#$ of rotations per unit of time

I is moment of inertia (inertia of rotating mass) $I = (\text{a coefficient})mr^2$

Angular momentum = $I\omega$ Conservation of Angular Momentum: $I_1\omega_1 = I_2\omega_2$